

# Introduction to the GMAT Project

GMAT Fundamentals  
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June 30, 2014

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# Presentation Overview

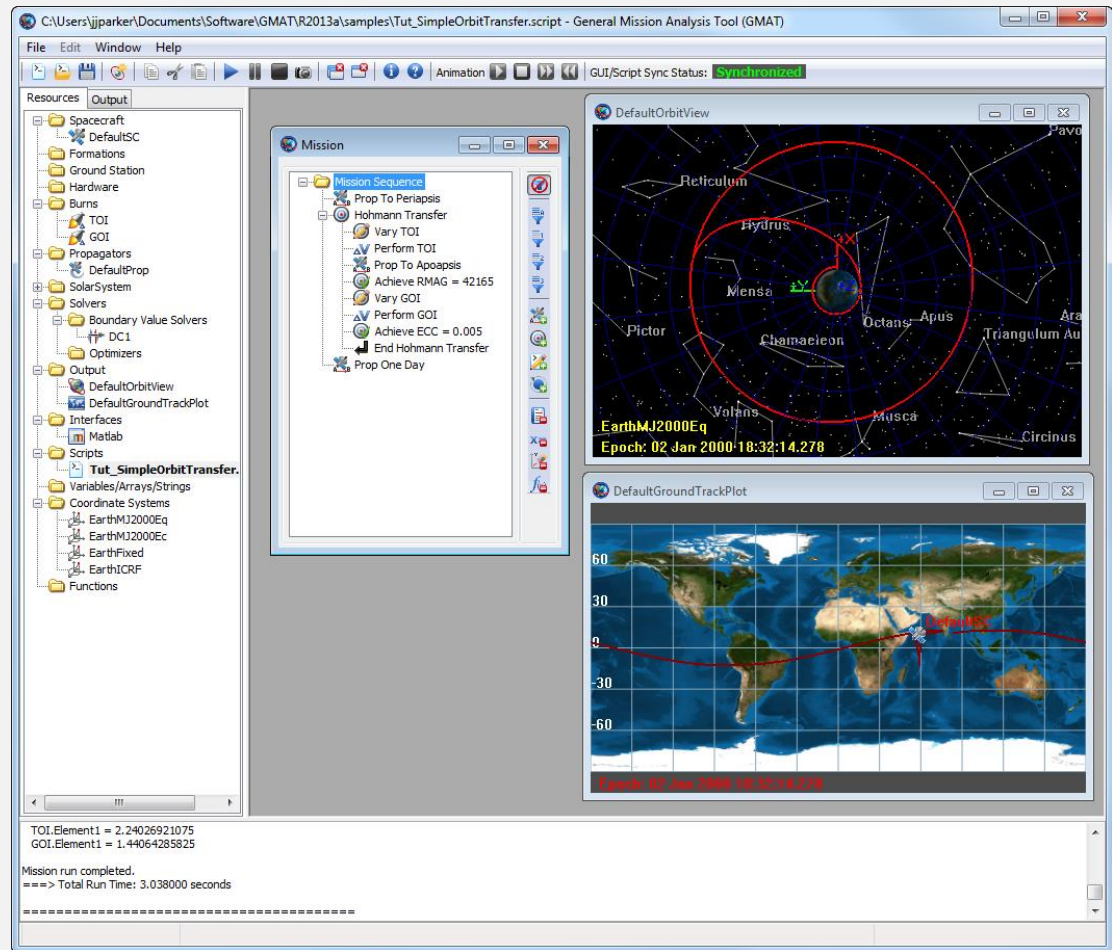
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# What is GMAT?

GMAT is a general mission design and analysis tool.

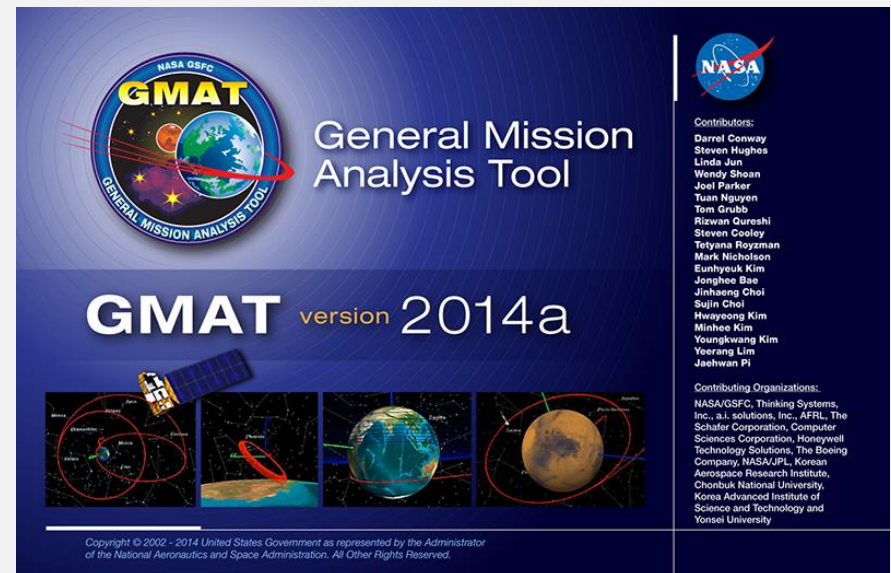
Key characteristics:

- open source
- high fidelity
- feature rich
- publicly developed
- desktop oriented



# System Overview

- Applications
  - Mission analysis/optimization
  - All orbital regimes
- Comparable to
  - AGI STK/Astrogator
  - A.I. Solutions FreeFlyer
- Functionality
  - Full-featured GUI
  - Custom script infrastructure
  - Cross-platform core
  - Precision orbit propagation
  - Built-in targeting & optimization
- Status: Fully tested and certified for operational use



# Key Features

## Basic Models

Spacecraft model	<ul style="list-style-type: none"><li>• Orbit state</li><li>• Kinematic attitude</li><li>• Mass properties</li><li>• Viz properties</li><li>• Attached hardware</li></ul>
Solar system	<ul style="list-style-type: none"><li>• User-defined bodies</li><li>• Libration points</li><li>• Barycenters</li><li>• SPK &amp; DE ephemerides</li></ul>
Coordinate systems	<ul style="list-style-type: none"><li>• Inertial</li><li>• Body-fixed</li><li>• Relative</li><li>• Rotating</li></ul>

## Propagation

Numerical integrators	<ul style="list-style-type: none"><li>• Runge-Kutta (several)</li><li>• Prince-Dormand (several)</li><li>• Adams-Bashforth-Moulton</li><li>• Prince-Dormand</li></ul>
Force models	<ul style="list-style-type: none"><li>• Third-body point-mass gravity</li><li>• Central-body non-spherical gravity</li><li>• Atmospheric drag</li><li>• Solar radiation pressure</li><li>• Earth tides</li><li>• Relativistic corrections</li></ul>
SPK ephemeris propagator	

# Key Features

## Powered Flight

Fuel tank w/ mass depletion

Thruster model

Impulsive burn

Finite burn

## Solvers

Targeting w/ differential correction

- |              |  |
|--------------|--|
| Optimization | <ul style="list-style-type: none"><li>• VF13 optimizer</li><li>• Interface to MATLAB fmincon optimizer</li><li>• Nonlinear constraints</li></ul> |
|--------------|--|

## Programming Infrastructure

User-defined variables

- Numeric
- Array
- String

Control flow

- If/Else
- While
- For

External interfaces

- Call MATLAB functions

Built-in math

Calculated parameters

# Project History

- 2001: Requirements gathering
- 2002: Architectural design
- 2003: Implementation of system core
- *...feature development...*
- 2010: Decision to prepare for operational use
- *...feature development...*
- 2013: First production release (R2013a)
- 2013: Operationally certified (ACE mission)
- Public releases:
  - 2007-08-23
  - 2007-12-10
  - 2008-09-30
  - R2011a (April 2011)
  - R2012a (May 2012)
  - R2013a (April 2013)
  - R2013b (Aug. 2013)
  - R2014a (May 2014)

# Participants/Contributors/Users

- Government
  - NASA Goddard
  - AFRL
  - JPL
  - ESA
  - KARI
- Industry
  - Thinking Systems, Inc.
  - Schafer Corporation
  - a.i. solutions
  - Numerica
  - Boeing
  - CSC
  - Honeywell
  - Decisive Analytics Corporation
- GSFC Flight Projects
  - LCROSS (backup tool)
  - ARTEMIS
  - LRO
  - OSIRIS
  - MMS
  - ACE
  - MAVEN
  - TESS (primary)
  - Future mission studies
- R2013a public release: ~400 downloads/mo.
- >30 published papers using GMAT results

# Development Metrics

- 14 active team members
  - 6 engineers (GSFC Code 595, A.I. Solutions)
  - 7 developers (Code 582/583, Thinking Systems)
  - 1 tester (A.I. Solutions)
- 450k lines of C++ code
- 12k public commits
- 11k automated script tests
- 4k automated GUI tests
- Nightly automated build/test process

# Recent Activities

- GMAT R2013a
  - First production (non-beta) release
  - Focused entirely on QA and documentation
  - Very few new features—but many improved
  - New support for ICRF coordinate systems
- GMAT R2013b (internal)
  - First operationally-certified release
  - Focused on ACE mission requirements
    - Initial state file reader
    - Binary-format ephemeris generator
- GMAT R2014a
  - New aligned-constrained coordinate system
  - New parameter types
- GMAT R2014a
  - Public release of all R2013b features
  - New KARI-developed features
    - State representations
    - Attitude models
  - Customizable orbit segment colors
  - Mars-GRAM 2005 atmosphere model
  - LHS parameter dependencies
  - New solver algorithms

# Near-Term Activities

- Large-scale features
  - Event location utility (w/ KARI)
  - GMAT functions
  - Low-thrust development (w/ KARI)
- Mission-specific development
  - TESS
  - MAVEN
  - JWST
- Navigation subsystem revitalization

# Project Resources

- Homepage & Wiki:  
<http://gmatcentral.org/>
- User Forums:  
<http://forums.gmatcentral.org/>
- Documentation:  
<http://gmat.sf.net/docs>
- Issue tracker:  
<http://bugs.gmatcentral.org/>

# Getting Involved

Easier

- Community support (forums, lists)
- Submit bugs, feature requests to JIRA
- Improve documentation
- Fix bugs, contribute to “starter” feature requests
- Contribute to new features

Harder